HeteroDoop: A MapReduce Programming System for Accelerator Clusters

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Motivation - Why MapReduce?

- Data explosion
- Needs distributed programming models and frameworks
- MapReduce offers ease of programming: Underlying framework (e.g. Hadoop), not the user, is responsible for
 - Parallelization (intra and inter node)
 - Ensuring data locality
 - Assuring fault tolerance
- MapReduce requirement: Only two operations Map (completely parallel), Reduce (partially parallel)

Motivation - Why Accelerators?

- Massive parallelism → good fit for Map
- High memory bandwidth (~10x of CPUs)
- High perf/watt (~5x of CPUs)
- · Commonplace, e.g. GPUs come built-in







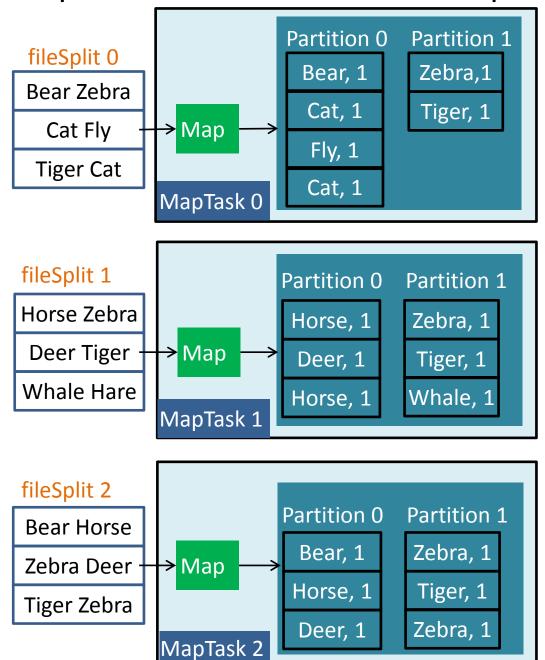
Hadoop

Most popular, open-source MapReduce implementation

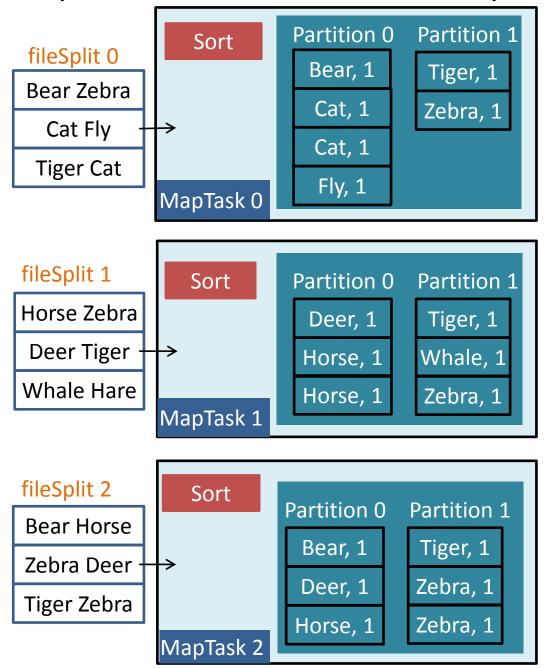
HDFS

- Hadoop Streaming
 - Requires just the executables for map, combine and reduce
 - User may write the program in any language adhering to Unix filter style (IO via STDIN/STDOUT)

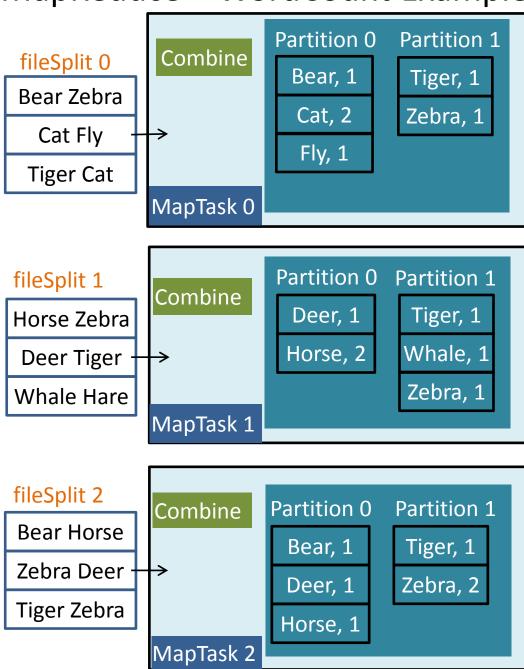
MapReduce – WordCount Example

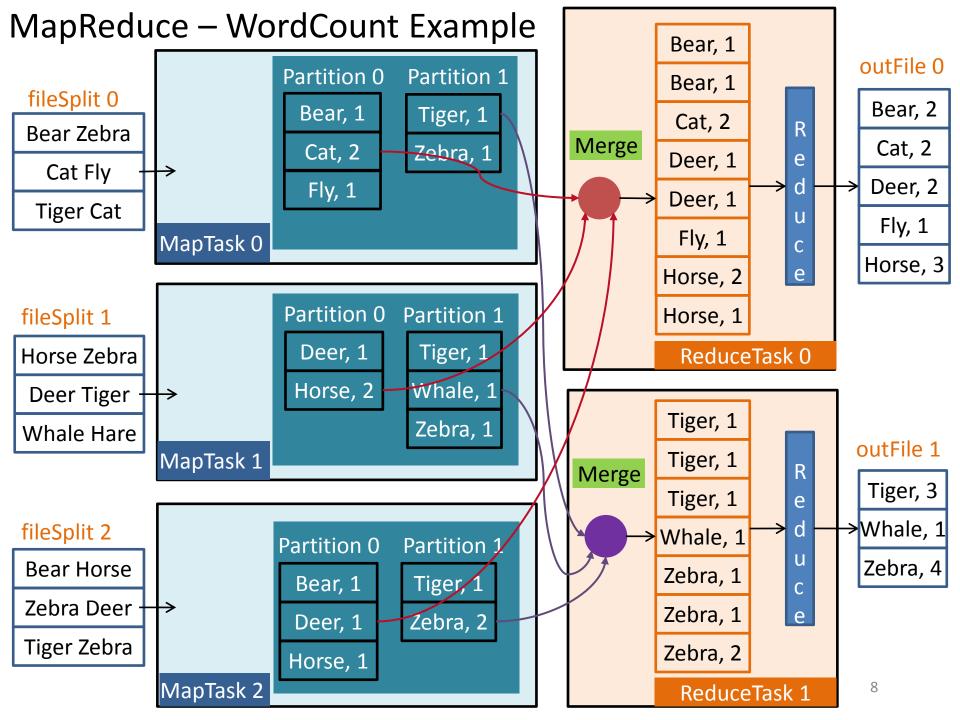


MapReduce – WordCount Example



MapReduce – WordCount Example





HeteroDoop: Challenges and Approach

- Accelerator programming models differ from those of CPUs. To exploit both, the user would have to write two program source codes
 - HeteroDoop offers program constructs so that a CPU-only program can now run on accelerators as well
 - An optimizing compiler translates codes to accelerator programs
- Parallelism exploitation in Hadoop : One fileSplit per core would exceed available GPU memory
 - Use record-level parallelism on the GPU, retain fileSplit-level parallelism for the CPU.
- Lack of MapReduce semantics for Accelerators
 - e.g. Intermediate sort
 - HeteroDoop contains a GPU-side runtime system
- Load Balancing: Accelerators are faster than CPUs
 - We present a tail scheduling scheme to optimize the execution

```
int main() {
                                                       WordCount
  char word[30], *line;
                                                       Map Code
  size t nbytes = 10000;
  int read, linePtr, offset, one;
  line = (char*) malloc(nbytes*sizeof(char));
                                                       CPU-only
  //read input file line by line
  while ((read = getline(&line, &nbytes, stdin)) != -1)
    linePtr = 0;
    offset = 0;
                                                    Independent
    one = 1;
                                                    Iterations
    while( (linePtr = getWord(line, offset, word,
      read, 30)) !=-1) {//read words in the line
      printf("%s\t%d\n", word, one); //emit <word, 1>
      offset += linePtr:
  free (line);
  return 0;
```

```
int main() {
                                                       WordCount
  char word[30], *line;
                                                       Map Code
  size t nbytes = 10000;
  int read, linePtr, offset, one;
  line = (char*) malloc(nbytes*sizeof(char));
  #pragma mapreduce mapper key(word) value(one) \\
  keylength (30) vallength (1)
                                                   CPU + Accelerator
  //read input file line by line
 while ((read = getline(&line, &nbytes, stdin)) !=-1) {
    linePtr = 0;
    offset = 0;
    one = 1;
    while ( (linePtr = getWord(line, offset, word,
      read, 30)) !=-1) {//read words in the line
      printf("%s\t%d\n", word, one); //emit <word, 1>
      offset += linePtr:
  free (line);
  return 0;
```

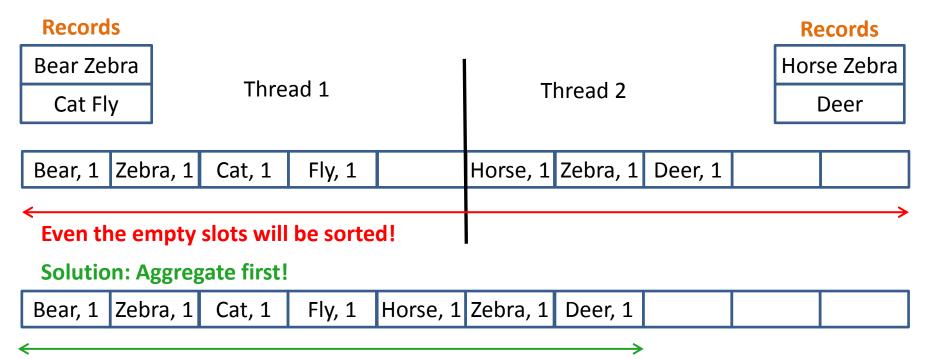
```
int main() {
                                                      WordCount
  char word[30], prevWord[30];
                                       CPU-only
                                                      Combine Code
  int count, val, read;
  //read map emitted KV pairs, which are already sorted
  while ( (read = scanf("%s %d", word, &val)) == 2 ) {
    if(strcmp(word, prevWord) == 0 ) {
      count += val; //sum up occurrences of the same word
    } else {
      if (prevWord[0] != ' \setminus 0')
        printf("%s\t%d\n", prevWord, count);
                                                 Data-dependence
      strcpy(prevWord, word);
                                                 is present
      count = val;
  if (prevWord[0] != ' \setminus 0')
    printf("%s\t%d\n", prevWord, count);
  return 0;
```

```
int main() {
                                  CPU + Accelerator
                                                     WordCount
  char word[30], prevWord[30];
                                                     Combine Code
  int count, val, read;
  #pragma mapreduce combiner key(prevWord) value(count)
 keyin(word) valuein(val) keylength(30) vallength(1)
  firstprivate(prevWord, count) {
  //read map emitted KV pairs, which are already sorted
 while( (read = scanf("%s %d", word, &val)) == 2 ) {
    if(strcmp(word, prevWord) == 0 ) {
      count += val; //sum up occurrences of the same word
    } else {
      if(prevWord[0] != '\0')
        printf("%s\t%d\n", prevWord, count);
      strcpy(prevWord, word);
      count = val;
  if (prevWord[0] != ' \setminus 0')
   printf("%s\t%d\n", prevWord, count);
  return 0;
```

- Low-level models (CUDA/OpenCL): Programmer has to
 - Manage CPU-Accelerator data transfers
 - Identify the parallelism and launch "kernels"
 - Exploit intricate memory hierarchy (e.g. shared, textures memories)
- High-level programming models (OpenMPC, OpenACC, OpenMP 4.0): Programmer has to
 - Identify parallelism
 - Lose out on architecture-specific optimizations
- Why not use OpenACC etc. for MapReduce?
 - Inherent mismatch : MapReduce programmers write only a serial code,
 OpenACC programmers write a parallel code
 - OpenACC does not understand MapReduce semantics, restricting the scope of optimizations.

Parallelization Strategies for the GPU Code

- Explicitly parallel
- Each thread works on different records and places output key-value (KV)
 pairs in its portion of a global KV store
 - Each thread has a portion in the global KV store for each partition
- Global KV store is conservatively over allocated



Parallelization Strategies for the GPU Code

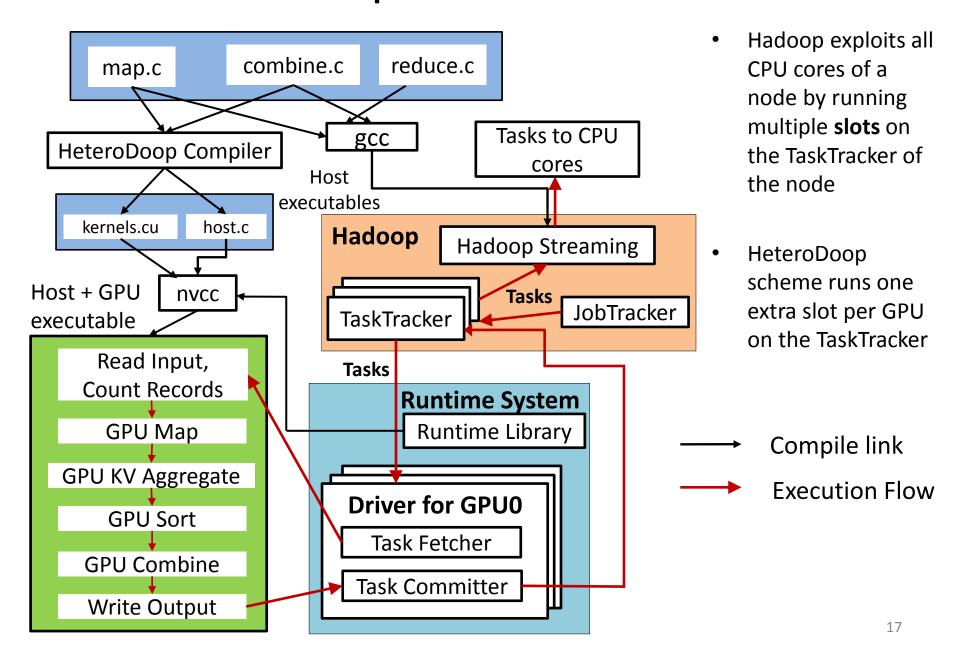
Combine

- Not explicitly parallel, but parallel across partitions
- We exploit reduction-style parallelism inside a partition
- Beneficial to run on the GPU since data is already present in the GPU memory

Reduce

- Only on the CPU
 - Data is NOT already on the GPU
 - Number of reducers is typically low → barely any parallelism to use GPUs

HeteroDoop Execution Scheme



HeteroDoop Compiler

Auto-translator from annotated C to CUDA

Built with Cetus

 Generates host (launcher) + device (kernel) code

 Generated code contains calls to functions of the runtime system

Compiler Optimizations

Map

- No shared writeable data

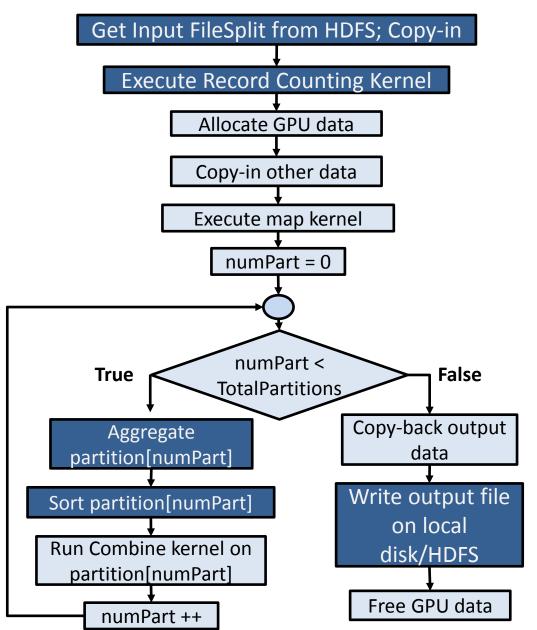
 All variables can be privatized
- Optimizations :
 - Dynamic record fetching (record stealing)
 - Use of CUDA vector data types (e.g. char4)

Combine

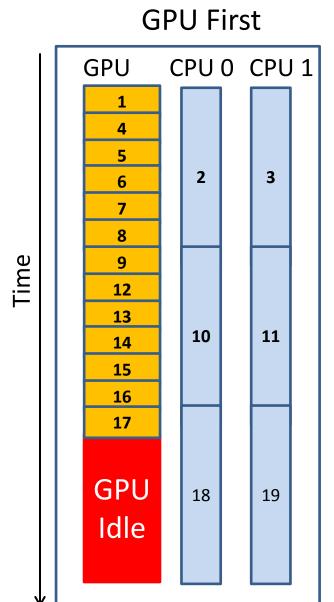
- Optimizations :
 - Less parallelism → Use 1 thread per warp → no warp divergence
 - Use remaining warp threads to vectorize certain operations e.g.
 KV read/write, strcpy etc.
 - Private arrays are placed in the GPU shared memory → faster access

Host Code Flowchart

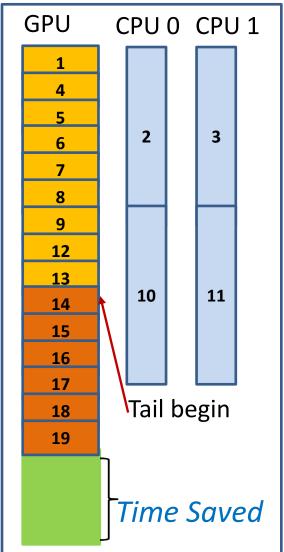
- Runtime System Call
- Host Code
- Runtime system supports kernel code by providing functions for:
 - read/write KVpairs
 - standard library
 functions for the
 GPU e.g. strcmp



Tail Scheduling







- GPU First naïve strategy where a GPU slot is preferred over a CPU slot
- Tail Scheduling:

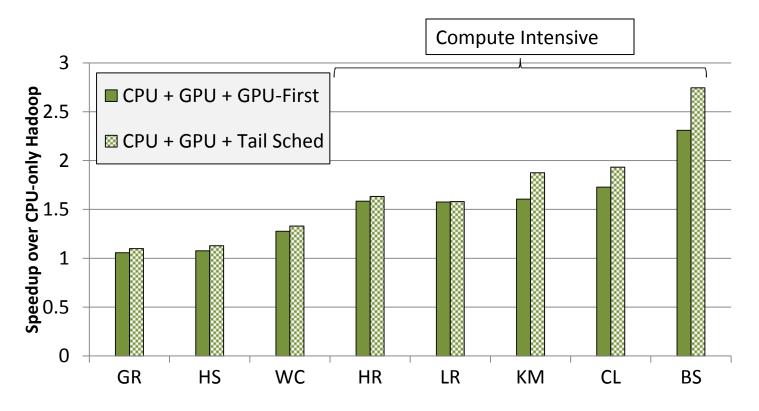
 Force tailing tasks
 on the GPU
- Tail size = GPU slot speedup over the CPU slot (6x in this example)

Evaluation: Setup

	Cluster1	Cluster2
#nodes	48 (+1 master)	32 (+1 master)
CPU	Intel Xeon E5-2680, 20 cores	Intel Xeon X5560, 12 cores
GPU	Tesla K40 (Kepler) New HW	3 x Tesla M2090 (Fermi) Old HW
RAM	256GB	24GB
Disk	500GB	None (in-memory system)
Network	FDR Infiniband	QDR Infiniband
HDFS Block Size	256 MB	256 MB
HDFS Replication Factor	3	1
Max. Map Slots	20 (+1 for GPU runs)	4 (+1 per GPU for GPU runs)
Max. Reduce Slots	2	2

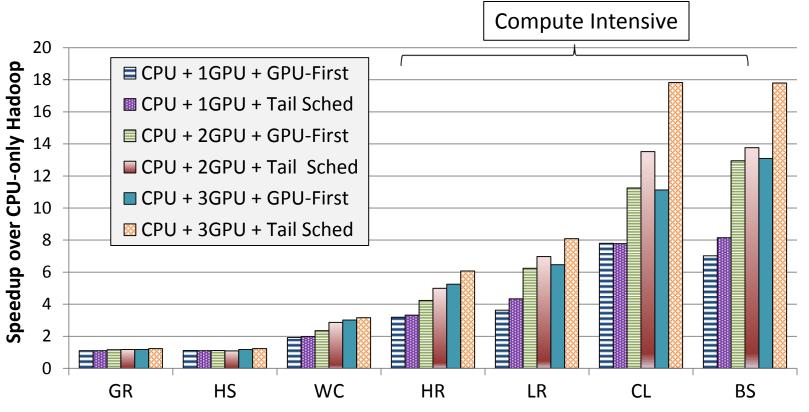
- Speculative execution was disabled
- Reduce phase was started after 20% map execution
- Cluster2: Used for evaluating multi-GPU scalability

Evaluation: Overall Benefits - Cluster1



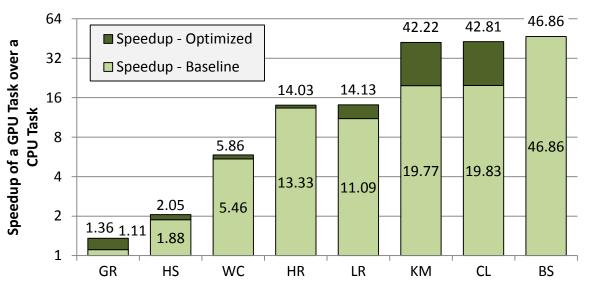
- Speedup with Tail Scheduling 1.6x (geo mean)
- Speedup with GPU-First 1.48x (geo mean)
- Higher speedups for compute-intensive applications

Evaluation: Overall Benefits – Cluster2

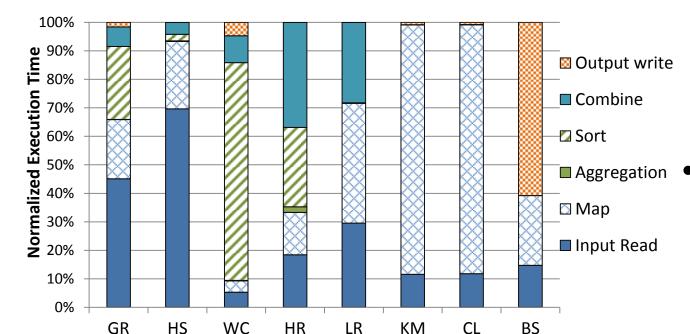


- Larger speedups than Cluster1 since Cluster2 uses less CPU cores
- Scalable performance with #GPUs

Individual Task Performance



 Single task speedup: max 47x



KM

HR

Optimizations can have a high impact

Bottlenecks are application dependent

Conclusion

HeteroDoop is a MapReduce programming system for accelerator clusters that features

- Single input source for the CPUs and GPUs
- Optimizing compiler to generate GPU program
- Runtime system to handle MapReduce semantics on GPUs
- Tail scheduling scheme that optimizes execution on an intra-node heterogeneous cluster



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